Radar Environment/Target Simulator KRATOS

Overview

The Kratos RT Logic Radar Environment and Target Simulator builds on an established line of propagation channel simulation products to realize an economical solution for simulating targets and channel effects in an RF environment. The system can be controlled via a standalone graphical user interface for simplified scenario applications, a dedicated real-time interface, or remotely via the Ethernet interface.

Features

- Support for L, S, C, X, and Ku radio frequency bands
- Frequency tuning and channel model updates within <300µs
- Amplitude and phase alignment between four RF channels
- Proven DRFM based architecture
- Scenario target update rates < 10ms
- Support for phased array beam steering emulation
- Supports multiple overlapping targets within a dwell
- Support for clutter and Swerling 0, I, II, III, and IV models
- Scenario input via GUI, Excel, MatLab, STK, or custom modeling tools

Applications

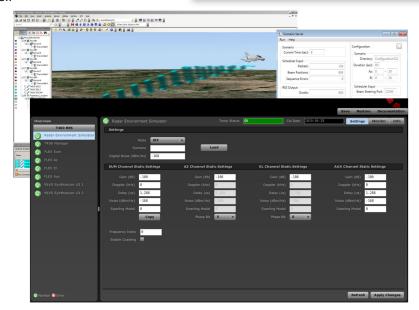
- Radar Environment and Flight Dynamics Simulation
- Monopulse Radar System Verification
- Multi-Channel Threat Generation
- RF Seeker Development and Verification
- Hardware In the Loop (HIL) Testing
- · Acceptance, Production, and Field Testing

Key Features

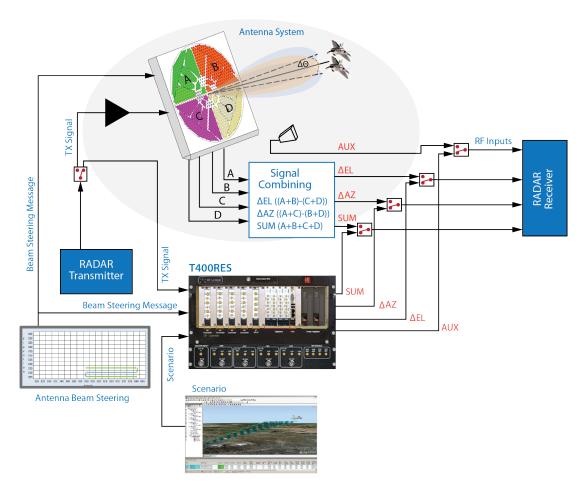
- Flexible Architecture supporting full turnkey systems or complementary subsystems
- **Customizable** with a wide range of HW and SW options
- **Scalable** allowing entry level systems to be upgraded to enhance capability
- Support for legacy and next generation platforms
- Robust TRL-9 solution

Proven Benefits

- Assured mission success
- Low risk with competitive cost
- Short lead time
- Extended lifecycle support



Mono-Pulse Radar Application Example



Specifications

Targets per Scenario Targets per Dwell

Beam Steering Resolution Scenario Target Update Rate

Scenario Length

Channel Model Update Rate

RF Frequency Range **RF Channels**

Antenna Patterns

Instantaneous Bandwidth

Pulse Width

Pulse Repetition Interval **In-Band Spurious**

Dynamic Range

Amplitude Resolution Doppler Range **Doppler Resolution**

Range Delay

Range Resolution

Phase Range Phase Resolution Programmable AWGN Range

AWGN Resolution

ADC 16 bits DAC

Up to 4 with independent target models

0.1 degrees

< 10 ms

Expandable with disk space

 $< 300 \, \mu s$

L, S, C, X, and Ku Bands Up To 4 per System Driven by scenario

> 100 MHz

 $< 1 \mu s$ to 500 μs , Pulsed CW, LFM, or CW

 $< 1 \mu s to > 10 ms$ better than -50 dBc

 $> 100 \, dB$ < 0.1 dB < +/- 5 MHz< 0.1 Hz

0.3 km to > 500 km

< 1 m

0 - 360 degrees < 0.1 degrees > 36 dB/Hz

0.5 dB 12 bits



